Positivity Preserving Numerical Method for Non-linear Black-Scholes Models

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Abstract. A motivation for studying the nonlinear Black- Scholes equation with a nonlinear volatility arises from option pricing models taking into account e.g. nontrivial transaction costs, investors preferences, feedback and illiquid markets effects and risk from a volatile (unprotected) portfolio. In this work we develop positivity preserving algorithm for solving a large class of non-linear models in mathematical finance on the original (infinite) domain. Numerical examples are discussed.

1 Introduction and Model Formulation

The solution of the (linear) Black-Scholes equation (Black and Scholes, 1973) has been derived under several restrictive assumptions like e.g. frictionless, liquid and complete markets, etc. We also recall that the linear Black-Scholes equation provides a perfectly replicated hedging portfolio. In the last decades some of these assumptions have been relaxed in order to model, for instance, the presence of transaction costs (see e.g. Leland [19], Avellaneda and Parás [5]), feedback and illiquid market effects due to large traders choosing given stock-trading strategies (Frey and Patie [10]), imperfect replication and investors preferences (Barles and Soner [6]), risk from unprotected portfolio (Jandačka-Ševčovič, [15]).

This models defer from the classical Black-Scholes equation by a non-constant volatility term σ , which depends on time t, spot price S of the underlying and the second derivative (Greek Γ) of the option price V(S, t). Hence, the model equation is the following nonlinear partial differential equation

$$V_t + \frac{1}{2}\sigma^2(t, S, V_{SS})S^2V_{SS} + (r - q)SV_S - rV = 0, \quad 0 \le S < \infty, \quad 0 \le t \le T, (1)$$

with constant short rate r, dividend yield q, maturity T and volatility $\sigma^2(t, S, V_{SS})$ depending on the particular model.

We will study (1) for European Call option, i.e. the value V(S, t) is the solution to (1), q = 0 on $0 \le S < \infty$, $0 \le t \le T$ with the following terminal and boundary conditions (E > 0 is the exercise price):

$$V(S,T) = \max\{0, S - E\}, \quad 0 \le S < \infty,$$

$$V(0,t) = 0, \quad 0 \le t \le T,$$

$$V(S,t) = S - Ee^{-r(T-t)}, \quad S \to \infty.$$
(2)

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The model (1) can be written as the backward parabolic fully nonlinear PDE $V_t + S^2 F(S, V_S, V_{SS}) = 0$. At some conditions on F, the most used of which are $F(S, p, r) \in C^2$, $V(S, T) = V_T(S)$, $F_r(S, V'_T(S), V''_T(S)) > 0$, in [1,2,6,15] was obtained results for existence and uniqueness of solutions (classical or viscosity). It was checked that the model described above satisfies these conditions.

Let $G(S, V_S, V_{SS}) = S^2 F(S, V_S, V_{SS}), G \in C^k((0, T) \times R^3)$. We briefly discuss the maximum principle (MP) for (1). Let Π_T be the rectangle $\Pi_T = \{(S, t) : 0 < t < T, -\infty < a < b < +\infty\}$ and $G_r(S, p, r) \ge 0$ everywhere and $G_r(S, 0, 0) = 0$. Then, if V is a classical solution of $V_t + G(S, V_S, V_{SS}) = 0$ in Π_T we have: $\max_{\Pi_T} V = \max_{\Gamma_T} u$ and $\min_{\Pi_T} V = \min_{\Gamma_T} V$, where $\Gamma_T = I \cup II \cup III, I = \{0 < t < T, x = a\}, II = \{a < x < b, t = 0\}, III = \{0 < t < T, x = b\}$ is the parabolic part of the boundary. For the proof, see [2].

There exists many discretizations, algorithms and some numerical methods for different versions of the non-linear Black-Scholes equation [4,7,8,12,14]. In [20], authors develop positivity-preserving (i.e. the non-negativity of the numerical solution to be guaranteed) first-order fully implicit scheme for models arising from pricing European options under transaction costs. In our previous work [17] we developed a *fast*, second order both in space and time a kernel-based method for solving a large class of non-linear models in mathematical finance, computed on large enough truncated region. But the non-negativity of the numerical solution is not guaranteed. In this work, having in mind MP discussed above, we will present efficient, *positivity preserving* algorithm for solving the same non-linear Black-Scholes models on the original (infinite) interval. We develop implicit-explicit methods on quasi-uniform mesh (QUM), implementing the idea of van Leer flux limiter [11,13,21].

An often used approach to overcome the *degeneration* at S = 0 and to obtain a *forward* parabolic problem, is the variable transformation [1,8,12]

$$x(S) = \log\left(\frac{S}{E}\right), \ \ \tau(t) = \frac{1}{2}\sigma_0^2(T-t), \ \ u(x,\tau) = e^{-x}\frac{V}{E}.$$

Now, denoting $K = 2r/\sigma_0^2$ (σ_0 is the volatility of the underlying asset), the equation (1) transforms into

$$u_{\tau} - \tilde{\sigma}^2(\tau, x, u_x, u_{xx})(u_x + u_{xx}) - Ku_x = 0, \quad x \in \mathbb{R}, \quad 0 \le \tau \le \frac{\sigma_0^2 T}{2},$$
 (3)

$$\begin{split} \widetilde{\sigma}_{\rm L}^2 &= 1 + f(u_x, u_{xx}), \qquad f(u_x, u_{xx}) = Le \cdot \operatorname{sign}(u_x + u_{xx}), \\ \widetilde{\sigma}_{\rm BS}^2 &= 1 + f(x, \tau, u_x, u_{xx}), \qquad f(x, \tau, u_x, u_{xx}) = \Psi[a^2 E e^{K\tau + x}(u_x + u_{xx})], \\ \widetilde{\sigma}_{\rm JS}^2 &= 1 + f(x, u_x, u_{xx}), \qquad f(x, u_x, u_{xx}) = \mu[Ee^x(u_x + u_{xx})]^{1/3}, \\ \widetilde{\sigma}_{\rm AP}^2 &= f(u_x, u_{xx}), \qquad f(u_x, u_{xx}) = \begin{cases} \sigma_{\max}^2, u_x + u_{xx} \le 0, \\ \sigma_{\min}^2, u_x + u_{xx} > 0, \end{cases} \\ \widetilde{\sigma}_{\rm FP}^2 &= f(x, u_x, u_{xx}), \qquad f(x, u_x, u_{xx}) = [1 - \rho \cdot \lambda(Ee^x)(u_x + u_{xx})]^{-2}, \end{split}$$

where $\tilde{\sigma}^2 = \tilde{\sigma}^2_{\text{L,BS,JS,AP,FP}}$ corresponds to Leland, Barles-Soner, Jandačka-Ševčovič, Avellaneda-Parás and Frey-Patie models, respectively. Here 0 < Le <