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► **To cite this version:**

Samy Blusseau, Santiago Velasco-Forero, Jesus Angulo, Isabelle Bloch. TROPICAL AND MORPHOLOGICAL OPERATORS FOR SIGNALS ON GRAPHS. 2018 25th IEEE International Conference on Image Processing (ICIP), Oct 2018, Athens, Greece. 10.1109/ICIP.2018.8451395 . hal-01799029v2

HAL Id: hal-01799029

<https://hal.science/hal-01799029v2>

Submitted on 1 Jun 2018

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TROPICAL AND MORPHOLOGICAL OPERATORS FOR SIGNALS ON GRAPHS

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ABSTRACT

We extend recent work on mathematical morphology for signal processing on weighted graphs, based on discrete tropical algebra. The framework is general and can be applied to any scalar function defined on a graph. We show applications in structure tensors analysis and the regularisation of greyscale images.

Index Terms— Mathematical morphology, signal processing on graphs, tropical algebra.

1. INTRODUCTION

Classical signal and image processing uses the natural geometry of the space supporting the signal (often Euclidean, or a regular discrete set) to define analysis operators such as differentiation, convolution, Fourier transform, interpolation. Processing a function supported by a graph requires to overcome the lack of regular geometrical structure, which leaves us without concepts as simple as translation, for example. Lately, signal processing on graphs has gained interest to address this kind of issues [1, 2, 3]. This effort includes the extension of non-linear operators, and in particular mathematical morphology, to signals on graphs [4].

Mathematical morphology (MM) first arose as a branch of non-linear image processing [5] and since then has been extended to a general mathematical framework based on lattice theory [6]. The formulation of morphological operators on graphs is a classical quest, but the previous formulations were mainly focused on unweighted graphs (use of graph structuring elements) [7] or based on max/min operations between vertices and edges weights [8]. The latter is appropriate to formulate watershed segmentation as a graph transform.

In [4] the authors introduce a formalism for MM for signals on graphs that generalises a wide range of mathematical morphology operators usually defined for images, including flat, non-flat and adaptive erosions and dilations. This formalism is clearly inspired by the idea of non-local morphology [9, 10]. Interestingly, although in [4] the authors do not emphasise this aspect, they write dilations and erosions as *max-plus* and *min-plus* “linear” functions, in other words as the product of a matrix by a vector in the “max-plus” and “min-plus” algebras, also called *idempotent* or *tropical* alge-

bras [11]. This is just a hint of how much the field of idempotent mathematics can be suited to the processing of signals on graphs from a mathematical morphology perspective. There are indeed strong links between idempotent algebras and optimal paths computations in graphs [12], as well as between these algebras and mathematical morphology [13, 14, 15, 16].

The goal of this paper is twofold. First, we introduce a general framework for morphological signal processing on graphs, using a tropical algebraic formulation. This opens the very rich field of max-plus algebra [17] to image processing and mathematical morphology. Secondly, we show two examples of applications based on the structure tensors of 2D images. One is the processing of the structure tensors anisotropy for the enhancement of fibre-like structures such as vessels. The second application is the morphological regularisation of greyscale images.

2. SETTING AND DEFINITIONS

2.1. Discrete max-plus algebra

We consider the semiring $\mathbb{R}_{\max} = \mathbb{R} \cup \{-\infty\}$ equipped with the two binary operations $x \oplus y = \max(x, y)$ and $x \otimes y = x + y$. The neutral element for \oplus is $-\infty$ ($\max(x, -\infty) = x$), which is also absorbing for \otimes ($x + (-\infty) = -\infty$), and the neutral element for \otimes is 0. What is more, both operations are associative and commutative, and \otimes is distributive over \oplus . Therefore in this setting the \oplus operation is the counterpart of the addition in the usual algebra, whereas \otimes is analogous to the multiplication. However one specificity of $(\mathbb{R}_{\max}, \oplus, \otimes)$ is the idempotency of the \oplus ($\max(x, x) = x$), for which it is called an idempotent semiring.

The set of matrices with elements in \mathbb{R}_{\max} also have their natural “max-plus” counterpart of linear operations, based on \oplus and \otimes . Let A and B be two $m \times n$ and $n \times p$ matrices, respectively. Then $A \odot B$ is the $m \times p$ matrix defined by $(A \odot B)_{ij} = \bigoplus_{k=1}^n a_{ik} \otimes b_{kj} = \max_{1 \leq k \leq n} (a_{ik} + b_{kj})$. For two matrices of the same size we also have the \oplus operation defined by $(A \oplus B)_{ij} = a_{ij} \oplus b_{ij} = \max(a_{ij}, b_{ij})$.

In the remaining of the paper we will note A^p the p -th power of a square matrix A in the max-plus sense, for any integer $p \geq 0$ (for $p = 0$, A^p is the max-plus identity matrix, for which $a_{ii} = 0$ and $a_{ij} = -\infty$ for $i \neq j$). The coefficients

of the matrix A^p will be noted $a_{ij}^{(p)}$. Finally, we will note $Mat_n(\mathbb{R}_{\max})$ the set of $n \times n$ matrices with elements in \mathbb{R}_{\max} . In this paper we focus on a particular class of square matrices, defined hereafter.

Definition 1 (Conservative morphological weight matrix [4])

A matrix $W \in Mat_n(\mathbb{R}_{\max})$ is a conservative morphological weight matrix if $-\infty \leq w_{ij} \leq 0$ and $w_{ii} = 0$ for any $(i, j), 1 \leq i, j \leq n$.

2.2. Graphs with conservative morphological weights

Let $G = (V, E)$ be a weighted and directed graph containing n vertices, whose $n \times n$ adjacency matrix, noted W , is a conservative morphological weight matrix (see Def. 1). We now recall and adapt a few definitions from graph theory.

A path from vertex i to vertex j in G is a tuple of vertices (k_1, \dots, k_l) such that $k_1 = i, k_l = j$, and $(k_p, k_{p+1}) \in E$ for $1 \leq p \leq l - 1$. We note Γ_{ij} the set of paths from i to j in G , and $\Gamma_{ij}^{(p)}$ the set of paths from i to j in G containing at most p vertices, $p \geq 1$. Given the weight matrix W , the weight of a path $\gamma = (k_1, \dots, k_l)$, noted $\omega(\gamma)$, is the sum $\omega(\gamma) = \sum_{p=1}^{l-1} w_{k_p, k_{p+1}}$. One can easily show that the set $\{\omega(\gamma), \gamma \in \Gamma_{ij}\}$ has a (finite) maximum value whenever Γ_{ij} is non empty. We call *maximal weight* and note $\omega^*(\Gamma)$ this value and a *maximal path* is a path achieving it. For completeness, we set $\omega^*(\emptyset) = -\infty$.

The following results show some strong links between tropical algebra and graphs. They can be found in various forms in the literature (e.g. [12, 18]) hence the proof is omitted here. We recall that the powers W^p are intended in the max-plus sense (Section 2.1).

Proposition 1 Let $p \in \mathbb{N}$. Then for any $1 \leq i, j \leq n$,

1. $w_{ij}^{(p)} > -\infty$ if and only if there is at least a path from vertex i to vertex j in G containing at most $p + 1$ vertices;
2. $w_{ij}^{(p)}$ is the maximal weight of the set of paths from vertex i to vertex j containing at most $p + 1$ vertices.

Interestingly, W^p is also a conservative morphological weight matrix. Its corresponding graph, that we note G^p , can be seen as the original graph G to which an edge is added between vertices i and j whenever there is a path containing at most $p + 1$ vertices from i to j . The weight associated with this new edge is $w_{ij}^{(p)} = \omega^*(\Gamma_{ij}^{(p+1)})$, the maximal weight for the paths from i to j containing at most $p + 1$ vertices. The following corollary is straightforward from the graph interpretation of the max-plus powers of W , given by Proposition 1.

Corollary 1 $W^n = W^{n-1}$ and therefore there exists an integer $p_{max} = \min\{p \in \mathbb{N}, W^p = W^{p+1}\}$.

Recall that n is the number of columns (or rows) of W . We will note $W^\infty \doteq W^{p_{max}} = W^{n-1}$. It is clear from Proposition 1 that $w_{ij}^{(\infty)} > -\infty$ if and only if there is a path from i

to j , and $w_{ij}^{(\infty)}$ is the maximal weight over the paths from i to j : $w_{ij}^{(\infty)} = \omega^*(\Gamma_{ij})$. What is more, one can easily check that $W^{p+1} \geq W^p$ and therefore $W^\infty = \bigoplus_{p \geq 0} W^p$ is the closure (or Kleene star [19]) of W , also noted W^* .

2.3. Morphological operators

In this section we link the max-plus product $W \odot \mathbf{x}$ (Section 2.1) to morphological operators on a vector \mathbf{x} supported by a graph G with conservative morphological weights (Section 2.2). This formulation, that will be summarised by Equation 3 (see *infra*) generalises many of the dilations and erosions defined on graphs and in image processing applications.

Mathematical morphology is usually defined on complete lattices [20]. A complete lattice (L, \leq) is a partially ordered set for which every subset $A \subseteq L$ has a supremum noted $\bigvee A$ and an infimum noted $\bigwedge A$. A mapping $\delta : L \rightarrow L$ is a dilation if it commutes with the supremum, and an erosion ε is an operator that commutes with the infimum: for a family $(\mathbf{x}_k)_{k \in K}$ of L , $\delta(\bigvee_{k \in K} \mathbf{x}_k) = \bigvee_{k \in K} \delta(\mathbf{x}_k)$ and $\varepsilon(\bigwedge_{k \in K} \mathbf{x}_k) = \bigwedge_{k \in K} \varepsilon(\mathbf{x}_k)$, where K is any index set.

We recall that W denotes a $n \times n$ conservative morphological weight matrix. We note $L = ([0, 1]^n, \leq)$ the complete lattice equipped with the usual product partial ordering (Pareto ordering): $\mathbf{x} \leq \mathbf{y} \iff x_i \leq y_i \ \forall i \in \{1, \dots, n\}$. The supremum and infimum on L are induced by the Pareto ordering: for a family $(\mathbf{x}^{(k)})_{k \in K}$ of L , $\bigvee_{k \in K} \mathbf{x}^{(k)}$ is the vector \mathbf{y} defined by $y_i = \bigvee_{k \in K} x_i^{(k)}$, which may not be any of the $\mathbf{x}^{(k)}$ (and the same holds for \bigwedge). Then the ‘‘max-plus-linear’’ function

$$\delta_W : \begin{cases} L & \rightarrow & L \\ \mathbf{x} & \mapsto & W \odot \mathbf{x} \end{cases} \quad (1)$$

is a dilation on L . Similarly, noting $\mathbf{x}^c = 1 - \mathbf{x}$,

$$\varepsilon_W(\mathbf{x}) = (W^T \odot \mathbf{x}^c)^c \quad (2)$$

is an erosion on L and the pair $(\varepsilon_W, \delta_W)$ forms an adjunction: $\forall \mathbf{x}, \mathbf{y} \in L, \delta_W(\mathbf{x}) \leq \mathbf{y} \iff \mathbf{x} \leq \varepsilon_W(\mathbf{y})$.

Let $\mathbf{x} = (x_1, \dots, x_n) \in L$ be a signal on G , meaning that each value x_i is supported by vertex i . Then the dilation and erosion of Equations 1 and 2 can be written for $1 \leq i \leq n$

$$\delta_W(x)_i = \max_{j \in \mathcal{N}_i} (x_j + w_{ij}), \quad \varepsilon_W(x)_i = \min_{j \in \mathcal{N}_j} (x_j - w_{ji}) \quad (3)$$

where $\mathcal{N}_i \doteq \{j \in \{1, \dots, n\}, (i, j) \in E\}$ is the set of neighbours of vertex i in G . At this point one should remember that the w_{ij} are non positive. The closer w_{ij} is to 0, the more likely vertex j is to contribute to the max (resp. the min) in the dilation (resp. erosion) of vertex i . Conversely, the closer w_{ij} is to $-\infty$, the more likely vertex j is to be irrelevant in these computations. In fact, the max can be taken over \mathcal{N}_i in the dilation because $w_{ij} = -\infty$ if $j \notin \mathcal{N}_i$, and the same holds

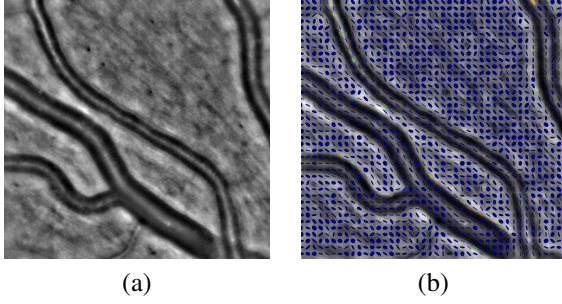


Fig. 1. (a) A greyscale image and (b) its structure tensors T_σ for $\sigma = 3$ pixels, obtained with [21]. The corresponding anisotropy image is shown in Figure 3 top left.

for the erosion. The dilation thus appears as a max-plus “non-local” convolution where coefficients w_{ij} model the weight of the neighbouring vertices in the graph. Note that Equation 3 generalises many adjunctions in image processing. For example, setting $w_{ij} = \log(\mathbb{1}_{\mathcal{B}_i}(j))$ with \mathcal{B}_i a structuring element for pixel i , we get the usual flat dilation and erosion. If the family $(\mathcal{B}_i)_{i \in I}$ is not translation invariant, we get the so called adaptive morphology framework; if \mathcal{B}_i is not a spatial neighbourhood of i , we get the typical non-local operators.

As it is well known in mathematical morphology, if a dilation δ and an erosion ε form an adjunction, then the dilation $\delta^p = \delta \circ \dots \circ \delta$ and the erosion $\varepsilon^p = \varepsilon \circ \dots \circ \varepsilon$ as well. The associativity of the max-plus product \odot yields the following result for these iterated dilation and erosion.

Proposition 2 *Let W a conservative morphological weight matrix, and $p \in \mathbb{N}$. Then $\delta_W^p = \delta_{(W^p)}$ and $\varepsilon_W^p = \varepsilon_{(W^p)}$.*

This also implies the semi-group property $\delta_{(W^p)}\delta_{(W^q)} = \delta_{(W^{p+q})}$, and an easy writing for δ_W^p and ε_W^p :

$$\delta_W^p(x)_i = \max_{j \in \mathcal{N}_i^p} (x_j + w_{ij}^{(p)}), \quad \varepsilon_W^p(x)_i = \min_{j, i \in \mathcal{N}_j^p} (x_j - w_{ji}^{(p)}) \quad (4)$$

where \mathcal{N}_i^p is the set of neighbours of vertex i in G^p or, equivalently, the set of vertices in G that can be reached from i through a path containing at most $p + 1$ vertices.

Since W^p is a conservative morphological weight matrix for any p , it is clear from Equation 4 that δ_W^p is extensive and ε_W^p is anti-extensive. From Corollary 1 and Proposition 2 we get the idempotence of $\delta_W^\infty \doteq \delta_{(W^\infty)}$ and $\varepsilon_W^\infty \doteq \varepsilon_{(W^\infty)}$, which are therefore a closing and an opening respectively, that verify $\delta_W^\infty \varepsilon_W^\infty = \varepsilon_W^\infty$ and $\varepsilon_W^\infty \delta_W^\infty = \delta_W^\infty$.

3. APPLICATION TO STRUCTURE TENSORS

In this section we introduce a class of graphs based on the co-circularity of the structure tensors principal directions. **Structure tensors and anisotropy image [21].** Given an image f , the scale zero tensor T_0 maps each pixel (x, y) to the symmetric positive semi-definite matrix with rank ≤ 1 ,

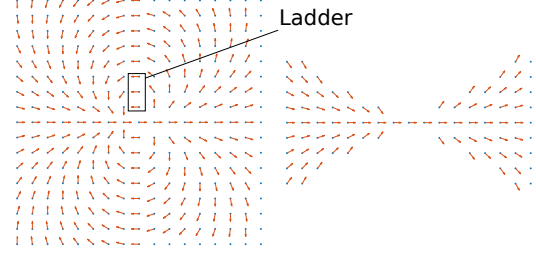


Fig. 2. **Left:** a set of elements (u, θ) co-circular to the central element (u_0, θ_0) where u_0 is the origin and $\theta_0 = 0$ rad; **Right:** the elements from the left hand image that comply with the additional constraint to avoid ladder configurations.

$T_0(x, y) = \nabla f(x, y) \cdot \nabla f(x, y)^T$. The gradient $\nabla f(x, y)$ is eigenvector of $T_0(x, y)$ with $\|\nabla f(x, y)\|^2$ as corresponding eigenvalue, and 0 is the other eigenvalue. Then for $\sigma > 0$ the tensor T_σ is the smoothed version $T_\sigma = G_\sigma * T_0$ where G_σ is the σ -scale Gaussian kernel. Note that, for any $u = (x, y)$, $T_\sigma(u)$ is a weighted sum of tensors $T_0(v)$ with positive weights, and is therefore a positive semi-definite matrix that can be represented by an ellipse (Fig. 1(b)). We note $0 \leq \lambda_2(u) \leq \lambda_1(u)$ the eigenvalues of $T_\sigma(u)$ and $(e_1(u), e_2(u))$ its basis of orthogonal eigenvectors. If we represent $T_\sigma(u)$ by its corresponding ellipse then its main direction is given by the second eigenvector $e_2(u)$. We note $\theta_2(u) = \arg(e_2(u))$. From the tensor field T_σ we can build the anisotropy image $I_a = \frac{\lambda_1 - \lambda_2}{\lambda_1 + \lambda_2}$. Then $0 \leq I_a \leq 1$, and the closer $I_a(u)$ to 1, the more $T_\sigma(u)$ is anisotropic (Fig. 3).

Co-circularity (Fig. 2). Given two points $u_1, u_2 \in \mathbb{R}^2$ and two angles θ_1, θ_2 we say that (u_1, θ_1) and (u_2, θ_2) are co-circular if there is a circle (with possibly infinite radius) tangent in u_1 and u_2 to the lines directed by the vectors $[\cos(\theta_1), \sin(\theta_1)]^T$ and $[\cos(\theta_2), \sin(\theta_2)]^T$, respectively.

An undirected graph with binary weights. The graph G we consider is built for an image containing n pixels. It is undirected and contains n vertices, one per pixel. Noting W its adjacency matrix, we set $w_{ij} = 0$ iff the point u_j is in a square window of fixed size $2k + 1$, centered on u_i , and $(u_i, \theta_2(i))$ and $(u_j, \theta_2(j))$ are co-circular up to a certain angular tolerance α , with an additional constraint to avoid ladder configurations (Figure 2). Otherwise, $w_{ij} = -\infty$.

3.1. Processing anisotropy

Processing an array of non-scalar data containing directional information is a complex task which can be of crucial interest. An example is tractography, which consists in tracking white matter fibres in 3D diffusion MRI of the brain [22]. Another possible application is the analysis of thin structures such as vessels in 2D images, through their sets of structure tensors (Figure 1 (b)). We present a method for the latter application, based on the operators defined in the previous sections.

As there is no meaningful ordering defining a complete

lattice on positive semi-definite matrices, we choose to perform a morphological analysis on scalar data inferred from the matrices. Thus we define the co-circularity graph as described above and the processed signal x_i on vertex i is the anisotropy of the structure tensor at pixel i . As Figure 3 shows (top row), anisotropy can be high even outside the relevant structures, and thresholding the image would not help identify the vessel. Our aim is to keep the anisotropy as high as possible in the vessels, while reducing it in the background. Figure 3 shows the resulting anisotropy after application of

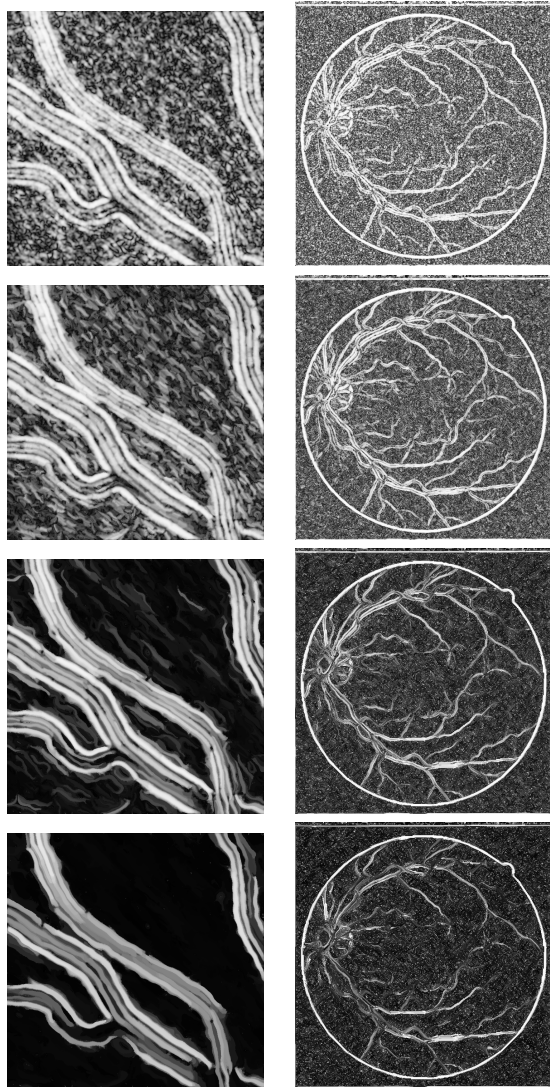


Fig. 3. Examples of openings $\gamma_W^{(p)}$ on anisotropy images, in the case of a binary and symmetric matrix W , computed as explained in Section 3. For each column, from top to bottom: $p = 0$ (original anisotropy image), $p = 1, 5, 10$.

openings $\gamma_W^{(p)} \doteq \delta_W^p \varepsilon_W^p$ for different values of p . As expected, for an appropriate p , the opening keeps brighter those vertices that are part of large and bright connected components in the



Fig. 4. Examples of openings $\gamma_W^{(p)}$ on a natural image, with W a binary and symmetric matrix, computed from the structure tensors as explained in Section 3. From top to bottom and left to right: $p = 0$ (original image), $p = 1, 2, 3$.

sense of the co-circularity graph. What is more, it produces homogeneous regions that match the structure of the vessels. This could be a useful pre-processing that could improve both segmentation and quantification.

3.2. Morphological anisotropic diffusion

Once the co-circularity graph is computed from the structure tensors, the operators defined earlier can also be applied to the original greyscale image, instead of doing so on the anisotropy image. This produces a regularising effect preserving the most salient edges. Figure 4 is an example of openings $\gamma_W^{(p)}$ applied to a landscape picture. Note that $\gamma_W^{(p)}$ is an idempotent operator, meaning that once p is chosen, the regularisation effect is obtained once and for all after one opening.

4. CONCLUSION

We introduced a framework that generalises mathematical morphology for signals on graphs, and that relies on a max-plus algebra formulation. This opens several questions such as the links between the properties of the weight matrix and those of the morphological operators. These questions shall be investigated with the support of the rich existing literature on idempotent mathematics and graphs, and also from the perspective of applications. The operators we defined based on the co-circularity of structure tensors show interesting behaviours for the processing of anisotropic structures and the morphological regularisation of natural images. However, further work is needed, as for example the development of a multi-scale approach or an automatic scale determination, as well as comparison with other methods.

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